



How Automation Technologies Improve Operating Efficiency and Reduce Collisions on Manned Forklifts

Reduce accidents and minimize costs from damage and downtime with backup sensing systems

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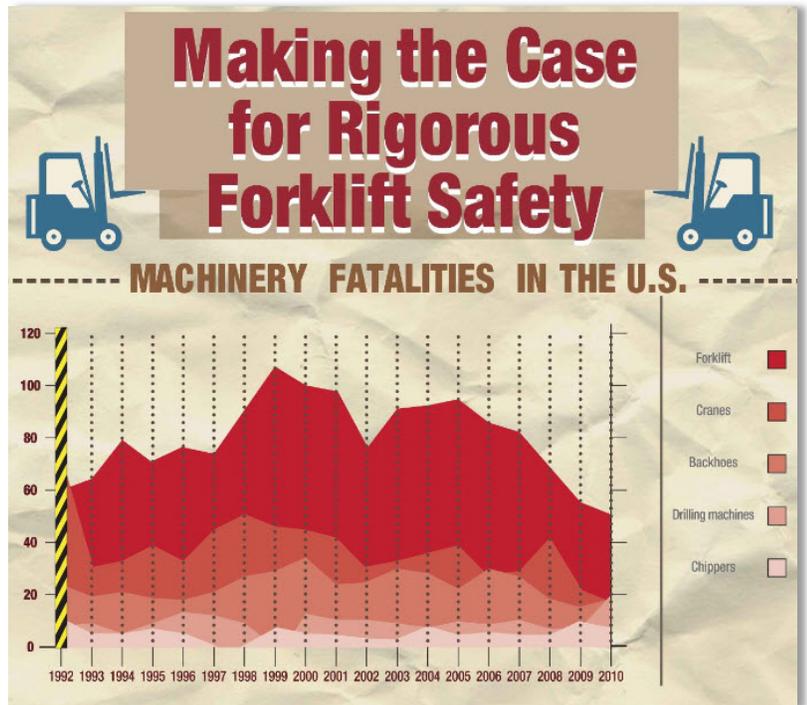
Increasingly competitive industrial environments are challenging warehouse and distribution center managers to reduce costs and increase productivity, while raising quality and safety standards. For facilities that cannot cost-justify a full conversion to completely automated unit load handling equipment, incorporating backup sensing technologies on forklifts can help maximize their efficiency.

That’s because adding active systems, such as backup sensing solutions to manned forklifts can reduce the risk of a forklift collision with objects behind the forklift, such as personnel, products, machinery or structures. There has been a growing interest by end users to equip manned forklifts with this technology on either new or existing equipment. No matter when the backup sensing technology is installed, its proper application and use, in combination with the driver, reduces collisions and minimizes downtime and expense associated with an accident.

This white paper will explain the available types of backup sensing solutions on manned forklifts, their respective advantages and disadvantages, the most common applications, and key considerations when selecting a system.

Why use automated technologies on manned trucks?

Statistics from the Industrial Truck Association (ITA) estimates that there are about 855,900 forklifts in operation in the U.S. According to the U.S. Occupational Health and Safety Administration (OSHA), those forklifts annually contribute to more than 100,000 accidents per year, which causes 94,750 injuries. Almost 80% of forklift accidents involve a pedestrian. In addition, should a forklift cause damage to inventory, the replacement costs can far exceed the value of the damaged items. For example, if the value of a case of goods damaged by a forklift collision is \$100, the cost to replace it must come from the margin on future sales. If the company makes a 1% margin on that case of goods, they will have to sell 100 additional cases to make up for that single damaged item.



Graphic: courtesy of Compliance and Safety-
[click here](#) to see the full graphic with more statistics about the importance of forklift safety.

According to OSHA, 70% of all forklift accidents could be avoided through standardized training and safety procedures. Even so, collisions continue to occur for a variety of reasons, including:

- OSHA standard 29 CFR 1910.178 (n)(4) for powered industrial trucks states: “If the load being carried obstructs forward view, the driver shall be required to travel with the load trailing.” However, even though forklift drivers are trained to always look in the direction of travel (and to travel in reverse if the load blocks their view), they may not do so consistently.
- Driver controls are frequently located on the fork-side of the lift truck; likewise, seats are oriented in the same direction. It can be ergonomically and physically difficult for a driver to twist around in their seat when backing up or traveling in reverse.



- There may be one or more blind spots, i.e. areas in the direction of travel that the driver cannot see without extra effort. Forklifts with enclosed cabins in particular can have blind spots caused by the protective structures between the windows.

- With more warehouses implementing high-density storage with narrower aisles, the turning radii may be compressed.

All these factors can contribute to collisions with “objects”, such as personnel, products or building structures (including racking, walls,

I-beams, roof supports and more).

Considerations when evaluating backup sensing technology options

To mitigate these risks, many companies have installed some type of object detection system, particularly on the back (non-fork) side of a manned forklift. These devices are intended to compensate for driver errors and eliminate costs associated with accidents. Two primary types of backup sensing technologies are available: passive and active.

Passive Systems

Passive camera systems include a box camera mounted on the back of the forklift. The images it records are transmitted to a viewing monitor in the cab of the forklift. This allows the driver to see what is behind the forklift without physically turning around. However, the driver has to make the judgment about when to apply the brakes. Many camera systems are limited to use in ambient temperatures, or must include a heating element to prevent the device from freezing or the lens from frosting over in cold storage environments. The forklift driver’s ability to detect obstacles can also be restricted by lighting conditions; dimly lit facilities, or highly reflective surfaces can impede a camera’s function. Dirt, dust and debris can also obscure the lens.

Other passive systems project a highly focused beam of light, or a laser, from the forklift onto the floor at a set distance away from the forklift. The light is intended as a visual cue for pedestrians that a forklift is approaching, alerting them to react appropriately. However, the light does not interact with static obstacles, such as facility structures, products or other equipment.

Another example of a passive system is the “reverse buzzer,” which most forklifts have integrated onto the machine. While this is commonly used and simple and easy to integrate, it is “always on” when the forklift is being driven in reverse. This provides good feedback to nearby personnel to minimize potential collisions; however, this annunciation does not help with static objects in the forklift’s path. Those collisions will still occur.

Active Systems

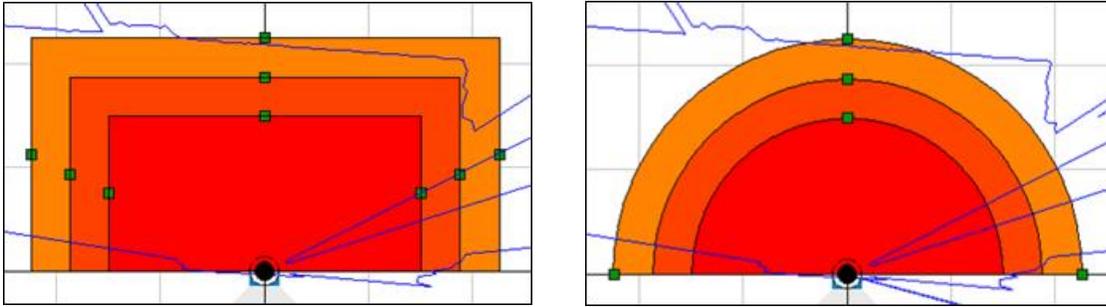
A wearable active warning system has been introduced that uses a proximity antenna, but there are some limitations since it requires a transponder “tag” to be worn by all personnel. In addition, an in-cab unit must be installed within each vehicle to read the personnel’s tag. If a person does not wear their transponder and enters the detection zone, an alarm will not be triggered. It is designed to reduce accidents between workers and vehicles, but placing tags on pallets and racks may not be feasible.

Alternately, active-sensing devices such as laser scanners continuously monitor a specific area behind the forklift. The technology projects a beam of infrared or invisible light away from the forklift. If the light encounters a surface, the surface reflects the light back to a sensor in the scanner. Internal converters and decoders interpret the collected information, utilizing intelligent algorithms to evaluate the field. These calculations determine the location of the obstacle relative to the position of the device on the forklift. Completely configurable, the projected eye-safe, invisible, 2D laser plane is capable of monitoring a rectangular or radial zone typically up to a 26-foot (8-meter) range in a 270° field of view to monitor the areas where obstructed views are present for the driver.

The laser scanners that are easiest to implement include push button control for easy teaching of detection areas, or zones. This means the user defines the dimensions of warning (and/or stopping) zones interactively—by putting the scanner in “teach mode” and walking the desired field’s shape in front of the scanner. Alternately, zone programming can be drawn using a graphical interface integrated with the scanner’s control software.

Once the teach-in process is complete, the scanner returns to an active monitoring mode. When the system detects an obstacle’s configured field, it triggers a warning to alert the driver to stop the forklift. Some systems provide 1- and 2-zone warnings (approaching a collision versus collision is imminent). The warning(s) could be a flashing light, horn, buzzer, bell, alarm, chime, or a combination (in 2-zone detection systems) of these. Also, these laser scanner systems can potentially be wired to the forklift’s stop circuit, triggering the forklift to automatically slow or stop if an obstacle is detected.





Active laser scanner sensing devices offer rectangular or radial zones of configurable size.

Additionally, laser scanners generally operate regardless of ambient light, reflective surfaces, dirt, dust, reliability in detecting various object colors and ambient noise immunity, but we suggest checking with the laser scanner supplier to verify this. Some can also be used in an operating temperature range of 14° to 122° Fahrenheit (-10° to 50° Celsius) for cold storage applications.

The backup system can be wired to the forklift's reverse gear circuit to eliminate false alarms caused by other closely-following vehicles moving in the same forward direction. Consider a backup system that is small in size and can fit virtually anywhere on a forklift. For laser scanners with 5W of power consumption, the backup system will not significantly diminish any of the other forklift's performance specifications. Alternately, the device can be operated by a separate power supply (for use with internal combustion forklifts).

Summary

When evaluating obstacle detection systems, either passive or active, consider the following points:

- Method of detection
- Types of detected obstacles – personnel, static objects
- Ease of forklift driver use
- Accuracy in low light conditions
- Reliability in dusty or dirty environments
- Function in cold temperatures
- Durability
- Ease of install and setup
- Power requirements (forklift battery draw)

Need more insights into how to select the right obstacle detection technology for your manned forklift fleet? Contact Michael Ing, Systems Applications Engineer, at SICK, Inc. BAS@sick.com or 800-325-7425

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