

English
Photoelectric proximity sensor
Operating Instructions

Safety notes

- Read the operating instructions before commissioning.
- Connection, mounting, and setting may only be performed by trained specialists.
- Not a safety component in accordance with the EU Machinery Directive.
- UL: The device shall be supplied from an isolating transformer having a secondary overcurrent protective device that complies with UL 248 to be installed in the fused outlet rating.
- a) max 5 amper for voltages 0 ~ 20 V (0 ~ 28.3 V peak), or
b) 100 / V₀ for voltages of 20 ~ 30 V(28.3 ~ 42.4 V peak).
- Alternatively, they can be supplied from a Class 2 power supply.
- UL Environmental Rating: Enclosure type 1.
- When commissioning, protect the device from moisture and contamination.
- These operating instructions contain information required during the life cycle of the sensor.

Correct use

The WTB4C-3Px(Axx) is an opto-electronic photoelectric proximity sensor (reflex sensor*) in the following for the optical, in-contact detection of objects, animals, and persons. If the product is used for any other purpose or modified in any way, any warranty claim against SICK AG shall become void.

Photoelectric proximity sensor with background suppression.

Commissioning

- Check the application conditions: Adjust the sensing range and distance to the object or background and the remission capability of the object according to the corresponding diagram [H] (x = sensing range, y = transition range between the set sensing range and suppression of the background as a % of the sensing range (object remission / background remission). Remission: 6% = gray (2), 18% = gray (2), 90% = white (1) (refer to standard DIN 5033)).
- The minimum distance ($= y$) for background suppression can be determined from diagram [H] as follows:

Examples: $x = 100 \text{ mm}$, $y = 7\%$ of $100 \text{ mm} = 7 \text{ mm}$. That is, the background is suppressed at a distance of > 107 mm from the sensor.

- Mount the sensor using a suitable mounting bracket (see the SICK range of accessories).
- Note the sensor's maximum permissible tightening torque of 0.8 Nm.
- Note the preferred direction of the object relative to the sensor (see A).
- The sensors must be connected in a voltage-free state ($U_s = 0 \text{ V}$). The information in the graphics [B] must be observed, depending on the type of connection:

 - Male connector connection pin assignment
 - Cable: core color

Operation in IO-Link mode:

Connect the device to a suitable IO-Link master and integrate in the master or control via IODD/function block. IODD and function block are available to download from www.sick.com under the part number.

Only apply voltage/switch on the voltage supply ($U > 0 \text{ V}$) once all electrical connections have been established. On the sensor, the green LED indicator (SI0 mode) lights up and starts to flash (IO-L mode). Explanations of the connection (Graphic B):

WTBAC-3Px(Axx)(Pin: load -> M)

C = Communication (e.g., IO-Link) (see Additional functions)

MF = multifunctional, programmable output

 - Align the sensor with the object. Select the position so that the red emission light beam hits the center of the object. You can ensure that the optical spot (front screen) of the sensor is completely clear [E]. We recommend making the adjustments using an object with a low reflectance.
 - Sensor with teach-in button:

The sensing range is adjusted by pressing the teach-in button. Do not operate the teach-in button using sharp objects. We recommend placing the switching state in the object, e.g., see graphic F. Once the sensing range has been adjusted, the object is removed from the path of the beam, which causes the background to be suppressed and the switching output to change (see graphic C).

Please refer to the enclosed operating instructions for the IO-Link photoelectric sensor for information about adjusting the IO-Link sensing range.

The sensor is adjusted and ready for operation. Refer to graphics C and G to check the function. If the switching output fails to behave in accordance with graphic C, check application conditions. See section Fault diagnosis.

Fault diagnosis

Table indicates which measures are to be taken if the sensor stops working.

Disassembly and disposal

The sensor must be disposed of according to the applicable country-specific regulations. Efforts should be made during the disposal process to recycle the constituent materials (particularly precious metals).

Maintenance

SICK sensors are maintenance-free.

We recommend doing the following regularly:

 - Clean the external lens surfaces
 - Check the screw connections and plug-in connections

No modifications may be made to devices.

Subject to change without notice. Specified product properties and technical data are not written guarantees.

Deutsch
Reflexions-Lichttaster
Betriebsanleitung

Sicherheitshinweise

 - Vor der Inbetriebnahme die Betriebsanleitung lesen.
 - Anschluss, Montage und Einstellung nur durch Fachpersonal.
 - Kein Sicherheitsbauteil gemäß EU-Maschinenrichtlinie.
 - UL: Das Gerät soll von einer isolierenden Transfomator mit einer sekundären Überstromschutzschaltung geliefert werden, die dem UL 248 entspricht.
 - a) max 5 amper für Spannungen 0 ~ 20 V (0 ~ 28.3 V Gipfel), oder
b) 100 / V₀ für Spannungen von 20 ~ 30 V(28.3 ~ 42.4 V Gipfel).
 - Alternativ, sie können von einer Klasse 2 Spannungsversorgung geliefert werden.
 - UL Umweltbewertung: Gehäuseart 1.
 - Bei Inbetriebnahme vor Feuchtigkeit und Verunreinigung schützen.
 - Diese Betriebsanleitung enthält Informationen, die während des Lebenszyklus des Sensors notwendig sind.

Bestimmungsgemäße Verwendung

Die WTB4-3 ist ein opto-elektronischer Reflexions-Lichttaster (im Folgenden Sensor genannt) und wird zum optischen, berührungslosen Erfassen von Sachen, Tieren und Personen eingesetzt. Bei jeder anderen Verwendung und bei Veränderungen am Produkt verfällt jeglicher Gewährleistungsanspruch gegenüber der SICK AG.

Reflexionslichttaster mit Hintergrundausblendung.

Inbetriebnahme

 - Einsatzbedingungen prüfen: Schaltabstand und Distanz zum Objekt bzw. Hintergrund sowie Remissionsvermögen des Objektes mit dem zugehörigen Diagramm (vgl. H) abgleichen (x = Schaltabstand, y = Übergangsbereich zwischen eingestelltem Schaltabstand und Ausblendung des Hintergrundes in % des Schaltabstands (Remission Objekt / Remission Hintergrund)). Remission: 6 % = schwarz (3), 18 % = grau (2), 90 % = weiß (1) (bezogen auf Standardweiß nach DIN 5033).
 - Die minimale Distanz (= y) für die Hintergrundausblendung kann aus dem Diagramm (vgl. H) wie folgt ermittelt werden:
 $Bereich = x + 100 \text{ mm}$, $y = 7 \% \text{ von } 100 \text{ mm} = 7 \text{ mm}$. d.h. der Hintergrund wird an einer Distanz von > 107 mm vom Sensor ausgebendet.
 - Den Sensor an einen geeigneten Befestigungswinkel montieren (siehe SICK-Zubehör-Programm).
Maximal zulässiges Anzugsdrehmoment des Sensors von 0.8 Nm beachten.
 - Vorzugsrichtung des Objektes zum Sensor beachten (siehe A).
 - Anschlüsse des Sensors müssen spannungsfrei ($U_s = 0 \text{ V}$) erfolgen. Je nach Anschlussart sind die Informationen in den Grafiken (vgl. B) zu beachten:
 - Steckerschlange: Pinbelegung
 - Leitung: Adernfarbe

Erst nach Anchluss aller elektrischen Verbindungen die Spannungsversorgung ($U_s > 0 \text{ V}$) anlegen bzw. einschalten. Am Sensor leuchtet die grüne Anzeige-LED.

Erläuterungen zum Anschlusschema (Grafik B):
Schaltausgänge Q bzw. Q' (gemäß Grafik B):
Teach = externer Teach (ET) (siehe Einstellung)
Vorzugsrichtung des Objektes zum Sensor beachten (siehe A).

3 Anschlüsse der Sensoren muss spannungsfrei ($U_s = 0 \text{ V}$) erfolgen.
Je nach Anschlussart sind die Informationen in den Grafiken (vgl. B) zu beachten:

 - Steckerschlange: Pinbelegung
 - Leitung: Adernfarbe

Erst nach Anchluss aller elektrischen Verbindungen die Spannungsversorgung ($U_s > 0 \text{ V}$) anlegen bzw. einschalten. Am Sensor leuchtet die grüne Anzeige-LED.

4 Align the sensor with the object. Select the position so that the red emission light beam hits the center of the object. You can ensure that the optical spot (front screen) of the sensor is completely clear [E]. We recommend making the adjustments using an object with a low reflectance.

5 Sensor with teach-in button:

The sensing range is adjusted by pressing the teach-in button. Do not operate the teach-in button using sharp objects. We recommend placing the switching state in the object, e.g., see graphic F. Once the sensing range has been adjusted, the object is removed from the path of the beam, which causes the background to be suppressed and the switching output to change (see graphic C).

Please refer to the enclosed operating instructions for the IO-Link photoelectric sensor for information about adjusting the IO-Link sensing range.

The sensor is adjusted and ready for operation. Refer to graphics C and G to check the function. If the switching output fails to behave in accordance with graphic C, check application conditions. See section Fault diagnosis.

Fault diagnosis

Table indicates which measures are to be taken if the sensor stops working.

Disassembly and disposal

The sensor must be disposed of according to the applicable country-specific regulations. Efforts should be made during the disposal process to recycle the constituent materials (particularly precious metals).

Maintenance

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A

Dimensions (mm):
Height: 39.5 (1.56)
Width: 12 (0.47)
Depth: 16 (0.63)
Mounting hole diameter: 9 (0.35)
Mounting hole distance: 11 (0.43)
Mounting hole depth: 0.29
Screw length: 11 (0.43)
Screw diameter: 0.25

Mounting holes:
① Top left
② Top right
③ Bottom left
④ Bottom right
⑤ Top left
⑥ Bottom left
⑦ Bottom right
⑧ Bottom left

Labels:
1 Standard direction of the material being detected
2 Optical axis, sender
3 Optical axis, receiver
4 Status indicator LED, yellow: Status of received light beam
5 Status indicator LED, green: power on
6 Teach-in button
7 Threaded mounting hole M3
8 Connection

B

	-P11x / -P12xx	-P22xx / -P24xx / -P32xx / -P34xx / -X22xx / -X32xx
bri ₁	+ (L+)	+ (L+)
bri ₁	Q ₁ /C	Q ₁ /C
wht ₁	MF	MF
blu ₁	(M)	(M)
blu ₂	(M)	(M)

C

Diagram illustrating the sensor's range and how it distinguishes between objects and backgrounds. It shows three objects (cubes) of different sizes and a background plane. The sensor's beam is directed towards the objects. The diagram shows the sensing range (x) and the transition range (y) for different object sizes. The background is suppressed when the object is within the sensing range.

D

Diagram illustrating the sensor's range and how it distinguishes between objects and backgrounds. It shows three objects (cubes) of different sizes and a background plane. The sensor's beam is directed towards the objects. The diagram shows the sensing range (x) and the transition range (y) for different object sizes. The background is suppressed when the object is within the sensing range.

E

Diagram illustrating the sensor's range and how it distinguishes between objects and backgrounds. It shows three objects (cubes) of different sizes and a background plane. The sensor's beam is directed towards the objects. The diagram shows the sensing range (x) and the transition range (y) for different object sizes. The background is suppressed when the object is within the sensing range.

F1

Diagram illustrating the sensor's range and how it distinguishes between objects and backgrounds. It shows three objects (cubes) of different sizes and a background plane. The sensor's beam is directed towards the objects. The diagram shows the sensing range (x) and the transition range (y) for different object sizes. The background is suppressed when the object is within the sensing range.

F2

Graph showing the relationship between sensing range (x) and transition range (y) in mm (inch). The x-axis ranges from 25 to 150 mm (0.98 to 5.91 inch). The y-axis ranges from 0 to 25 mm (0 to 1 inch). Three curves are shown:
 1. Top curve: 6% / 90% (white line)
 2. Middle curve: 18% / 90% (gray line)
 3. Bottom curve: 90% / 90% (black line)

H

Graph showing the relationship between sensing range (x) and transition range (y) in mm (inch). The x-axis ranges from 25 to 150 mm (0.98 to 5.91 inch). The y-axis ranges from 0 to 25 mm (0 to 1 inch). Three curves are shown:
 1. Top curve: 6% / 90% (white line)
 2. Middle curve: 18% / 90% (gray line)
 3. Bottom curve: 90% / 90% (black line)

I

Anzeige-LED / Fehlerbild / Ursache / Maßnahme /	LED indicator/fault pattern / Cause / Measures
grüne LED leuchtet nicht / keine Spannung oder Spannung unterhalb der Grenzwerte /	grüne LED does not light up / No voltage or voltage below the limit values
Spannungsunterbrechungen / Spannungsunterbrechungen /	Check the power supply; check all electrical connections (cables and plug connections)
grüne LED leuchtet nicht / Vorsicht! Spannungsunterbrechungen /	Sicherstellen einer stabilen Spannungsversorgung ohne Unterbrechungen / Ensure there is a stable power supply without interruptions
grüne LED leuchtet nicht / Sensor ist defekt /	Wenn Spannungsversorgung in Ordnung ist, dann Sensor austauschen / If the power supply is OK, replace the sensor
grüne LEDs flaschen / IO-Link communication	-
Switching outputs not according to graphic C / Switching outputs not according to graphic C	-
gelbe LED blinkt / Yellow LED flashes	Initiate a factory reset. The switching outputs are reset to their factory settings
gelbe LED blinkt (nur kurz) / Yellow LED flashes (only briefly)	Check the teach-in mode
gelbe LED leuchtet, kein Objekt im Strahlengang / gelbe LED lights up, no object in the path of the beam	Abstand zwischen Sensor und Hintergrund ist zu gering / Distance between the sensor and the background is too short
Objekt ist im Strahlengang, gelbe LED leuchtet nicht / Objekt ist in the path of the beam, yellow LED does not light up	Abstand zwischen Sensor und Objekt ist zu groß oder Schaltabstand ist zu gering eingestellt / Distance between the sensor and the object is too long or sensing range is set too short

J

Teach-In-Modus für Objekte / Teach-In mode for objects	Teach-In-Zeit / Teach-in time	Ausrichtung / Alignment	Anzeige-LED / LED indicator	Ergebnis / Results
Einfach-Teach-in/Taste / Single teach-in/pushbutton	ca. 1.0 s / Approx. 1.0 s	Sensor auf Objekt / Sensor to object	Schaltabstand wird auf Objekt eingestellt / Sensing range is adjusted according to object	
Wenn ET aktiviert: Pin 2 oder weiße Ader auf UV legen (PNP) / If ET activated: Connect pin 2 or white wire to UV (PNP)	ca. 1.0 s / Approx. 1.0 s	Sensor auf Objekt / Sensor to object	Schaltabstand wird auf Objekt eingestellt / Sensing range is adjusted according to object	

K

Sensing range	Schaltabstand	Distance de commutation	Distância de comutação	Distancia de comutación	开关距离	输出范围	Räumliche Schaltabstände
Sensing range max.	Schaltabstand max.	Portée max.	Distância de comutação máx.	Distância de comutación máx.	最大开关距离	最大输出范围	
Light spot diameter/distance	Lichtfleckendurchmesser/Entfernung	Diamètre du point lumineux/distância	Diámetro do ponto luminoso/distância	光斑直径/距离	光点的直径/距离		
Voltage supply U _s	Versorgungsspannung U _s	Tension d'alimentation U _s	Tensão de alimentação U _s	供电电压 U _s	供电电压 U _s		
Output current I _{out}	Ausgangsstrom I _{out}	Courant de sortie I _{out}	Corrente de saída I _{out}	输出电流 I _{out}	输出电流 I _{out}		
Communication mode	Kommunikationsmodus	Mode de communication	Modo de comunicação	通信模式	通信モード		
IO-Link	IO-Link	IO-Link	IO-Link	IO-Link	IO-Link		
Max. switching frequency	Schaltfolge max.	Commutation max.	Sequência máx. de comutação	Secuencia máx. de comutación	最大开关操作频率	最大切换频率	
Max. response time	Ansprichtzeit max.	Temps de réponse max.	Tempo máx. de resposta	最长响应时间	最长响应时间		
Enclosure rating	Schutzart	Indice de protección	Tipo de protección	防护等级	クラス защиты		
Protection class	Schutzklassen	Classe de protección	Classe de proteção	防护等级	クラス защиты		
Circuit protection	Schutzschaltungen	Protections électriques	Circuitos de protección	保护电路	保護回路		
Ambient operating temperature	Betriebsumgebungstemperatur	Température ambiante de fonctionnement	Temperatura ambiente de funcionamiento	周围环境温度	周辺環境温度(作動中)		
					Diapason de travail température		

L

Sensing range	Schaltabstand	Distance de commutation	Distância de comutação	Distancia de comutación	开关距离	输出范围	Räumliche Schaltabstände
Sensing range max.	Schaltabstand max.	Portée max.	Distância de comutação máx.	Distância de comutación máx.	最大开关距离	最大输出范围	
Light spot diameter/distance	Lichtfleckendurchmesser/Entfernung	Diamètre du point lumineux/distância	Diámetro do ponto luminoso/distância	光斑直径/距离	光点的直径/距离		
Voltage supply U _s	Versorgungsspannung U _s	Tension d'alimentation U _s	Tensão de alimentação U _s	供电电压 U _s	供电电压 U _s		
Output current I _{out}	Ausgangsstrom I _{out}	Courant de sortie I _{out}	Corrente de saída I _{out}	输出电流 I _{out}	输出电流 I _{out}		
Communication mode	Kommunikationsmodus	Mode de communication	Modo de comunicação	通信模式	通信モード		
IO-Link	IO-Link	IO-Link	IO-Link	IO-Link	IO-Link		
Max. switching frequency	Schaltfolge max.	Commutation max.	Sequência máx. de comutação	Secuencia máx. de comutación	最大开关操作频率	最大切换频率	
Max. response time	Ansprichtzeit max.	Temps de réponse max.	Tempo máx. de resposta	最长响应时间	最长响应时间		
Enclosure rating	Schutzart	Indice de protección	Tipo de protección	防护等级	クラス защиты		
Protection class	Schutzklassen	Classe de protección	Classe de proteção	防护等级	クラス защиты		
Circuit protection	Schutzschaltungen	Proteções eléctriques	Comunidades de protección	保护电路	保護回路		
Ambient operating temperature	Betriebsumgebungstemperatur	Température ambiante de fonctionnement	Temperatura ambiente de servicio	工作环境温度	周辺環境温度(作動中)		

M

Sensing range	Schaltabstand	Distance de commutation	Distância de comutação	Distancia de comutación	开关距离	输出范围	Räumliche Schaltabstände
Sensing range max.	Schaltabstand max.	Portée max.	Distância de comutação máx.	Distância de comutación máx.	最大开关距离	最大输出范围	
Light spot diameter/distance	Lichtfleckendurchmesser/Entfernung	Diamètre du point lumineux/distância	Diámetro do ponto luminoso/distância	光斑直径/距离	光点的直径/距离		
Voltage supply U _s	Versorgungsspannung U _s	Tension d'alimentation U _s	Tensão de alimentação U _s	供电电压 U _s	供电电压 U _s		
Output current I _{out}	Ausgangsstrom I _{out}	Courant de sortie I _{out}	Corrente de saída I _{out}	输出电流 I _{out}	输出电流 I _{out}		
Communication mode	Kommunikationsmodus	Mode de communication	Modo de comunicação	通信模式	通信モード		
IO-Link	IO-Link	IO-Link	IO-Link	IO-Link	IO-Link		
Max. switching frequency	Schaltfolge max.	Commutation max.	Sequência máx. de comutação	Secuencia máx. de comutación	最大开关操作频率	最大切换频率	
Max. response time	Ansprichtzeit max.	Temps de réponse max.	Tempo máx. de resposta	最长响应时间	最长响应时间		
Enclosure rating	Schutzart	Indice de protección	Tipo de protección	防护等级	クラス защиты		
Protection class	Schutzklassen						

Fransais	Português	Italiano	Español	中文	日本語	Русский язык
détecteur en réflexion directe Notice d'instruction	sensor de reflexão Manual de Instruções	Sensore di luce a riflessione Istruzioni per l'uso	Sensor fotoeléctrico de reflexión Instrucciones de uso	反射式光電傳感器 操作說明	反射形光センサ 取扱説明書	Отражательный световой датчик Руководство по эксплуатации
Consignes de sécurité						
<p>Lire la notice d'instruction avant la mise en service.</p> <ul style="list-style-type: none"> Confier le raccordement, le montage et le réglage uniquement à un personnel spécialisé. Il ne s'agit pas d'un composant de sécurité au sens de la directive machines CE. Le device shall be supplied from an isolating transformer having a secondary overcurrent protective device that complies with UL 248 to be installed in the field rated either: <ul style="list-style-type: none"> a) max 5 amps for voltages 0 ~ 20 V (0 ~ 28.3 V peak), or b) 100 / Vp for voltages of 20 ~ 30 V (28.3 ~ 42.4 V peak) <p>Alternatively, they can be supplied from a Class 2 power supply. UL Environmental Rating: Enclosure type 1.</p> Durante o funcionamento, manter o aparelho protegido contra impurezas e umidade. Este manual de instruções contém informações necessárias para toda a duração do ciclo de vida do sensor fotoelétrico. detec4 core 						
Utilisation conforme						
WTB4-3 est un détecteur à réflexion directe optoélectronique (appelé capteur dans ce document) qui permet la détection optique sans contact d'objets, d'animaux et de personnes. Toute autre utilisation ou modification du produit annule la garantie de SICK AG. Détecteur à réflexion directe avec élimination d'arrière-plan.	O WTB4-3 é um sensor fotocelular de proximidade utilizado para a deteção óptica, sem contato, de objetos, animais e pessoas. Qualquer utilização diferente ou alteração do produto provocam a perda da garantia da SICK AG. Sensor de luz de reflexão com supressão de fundo.	WTB4-3 è uno sensore fotocellulare a riflessione ottica (di seguito nominato "sensore") che permette la detezione ottica senza contatto di oggetti, animali e persone. Se viene utilizzata diversamente e in caso di modifica del prodotto, la garanzia della SICK AG viene annullata. Rilevatore ottico a riflessione con soppressione dello sfondo.	WTB4-3 es un sensor fotoeléctrico de proximidad que se utiliza para la detección óptica sin contacto de objetos, animales y personas. Cualquier uso diferente al previsto o modificación en el producto invalidará la garantía por parte de SICK AG. Detector de luz de reflexión con supresión de fondo.	WTB4-3 是一种漫反射式光电传感器（下文简称“传感器”），用于物体、动物和人体的非接触式光学检测。如果将产品或擅自更改产品，则 SICK AG 所作之质保将均失效。	WTB4-3 は反射形光センサ（以下「センサ」）で、物体、動物または人々などを光学的技術により非接触で検知するための装置です。本製品が本来の使用用途以外に目的に使用されたり、何らかの方法で改変された場合、SICK AG に対するいかなる保証要求も無効になります。	Данное руководство по эксплуатации содержит информацию, которая необходима во время всего жизненного цикла сенсора.
Mise en service						
WTB4-3 est un détecteur à réflexion directe optoélectronique (appelé capteur dans ce document) qui permet la détection optique sans contact d'objets, d'animaux et de personnes. Toute autre utilisation ou modification du produit annule la garantie de SICK AG. Détecteur à réflexion directe avec élimination d'arrière-plan.	O WTB4-3 é um sensor fotocelular de proximidade utilizado para a deteção óptica, sem contato, de objetos, animais e pessoas. Qualquer utilização diferente ou alteração do produto provocam a perda da garantia da SICK AG. Sensor de luz de reflexão com supressão de fundo.	WTB4-3 è uno sensore fotocellulare a riflessione ottica (di seguito nominato "sensore") che permette la detezione ottica senza contatto di oggetti, animali e persone. Se viene utilizzata diversamente e in caso di modifica del prodotto, la garanzia della SICK AG viene annullata. Rilevatore ottico a riflessione con soppressione dello sfondo.	WTB4-3 es un sensor fotoeléctrico de proximidad que se utiliza para la detección óptica sin contacto de objetos, animales y personas. Cualquier uso diferente al previsto o modificación en el producto invalidará la garantía por parte de SICK AG. Detector de luz de reflexión con supresión de fondo.	WTB4-3 是一种漫反射式光电传感器（下文简称“传感器”），用于物体、动物和人体的非接触式光学检测。如果将产品或擅自更改产品，则 SICK AG 所作之质保将均失效。	WTB4-3 は反射形光センサ（以下「センサ」）で、物体、動物または人々などを光学的技術により非接触で検知するための装置です。本製品が本来の使用用途以外に目的に使用されたり、何らかの方法で改変された場合、SICK AG に対するいかなる保証要求も無効になります。	Данное руководство по эксплуатации содержит информацию, которая необходима во время всего жизненного цикла сенсора.
Colocação em funcionamento						
1 Vérifier les conditions d'utilisation : comparer la portée et la distance à l'objet à l'arrière-plan et les caractéristiques de réflexivité avec le diagramme correspondant [cp. H] (= zone de communication, y = zone de transmission entre la portée réelle et le masquage de l'arrière-plan en % de la portée réelle de l'objet / réflexivité de l'arrière-plan). Réflexivité : 6% = noir (3), 18% = gris (2), 90% = blanc (1) (par rapport au blanc standard DIN 5033).	1 Verificar as condições d'uso: comparar a distância e a distância à objecto ou plano de fundo, bem como a refletividade do objecto, com o respectivo diagrama [cp. H] (= área de comunicação, y = área de transição entre a distância de comunicação ajustada e a supressão do fundo em % da distância de comunicação (luminância do objecto / luminância do fundo)). Refletividade: 6% = preto (3), 18% = cinza (2), 90% = branco (1) (com base no padrão branco da norma DIN 5033).	1 Controllare le condizioni d'impiego: confrontare la distanza di comunicazione e la distanza dall'oggetto con il relativo diagramma [cfr. H] (= area di comunicazione, y = area di transizione tra la distanza di comunicazione impostata e la soppressione dello sfondo in % della distanza di comunicazione (luminosità dell'oggetto / luminosità del fondo)). Refletività: 6% = nero (3), 18% = grigio (2), 90% = bianco (1) (rispetto alla bianchezza standard secondo DIN 5033).	1 檢查使用條件：使能通訊距離和背景抑制距離與圖表 [參照 H] 調整開關距離和物體距離。（ x = 物體距離， y = 已設置的開關距離和背景抑制距離）。	1 檢查使用條件：使能通訊距離和背景抑制距離與圖表 [參照 H] 調整開關距離和物體距離。（ x = 物體距離， y = 已設置的開關距離和背景抑制距離）。	1 檢查使用條件：使能通訊距離和背景抑制距離與圖表 [參照 H] 調整開關距離和物體距離。（ x = 物體距離， y = 已設置的開關距離和背景抑制距離）。	1 Проверить условия применения: скорректировать расстояние до срабатывания и дистанцию до объекта / фоном, а также яркость объекта с помощью соответствующей диаграммы [см. H] (= «растояние до срабатывания, y = «расстояние до объекта / фоном») в соответствии с изображением на рисунке [см. H].
La distance minimale (y) pour l'élimination d'arrière-plan peut être calculée à partir du diagramme [E] comme suit :	A distância mínima (y) para a supressão de fundo pode ser determinada a partir do diagramma [cp. E] da seguinte:	La distanza minima (y) per la soppressione dello sfondo può essere rilevata dal diagramma [fig. H] come segue:	La distanza minima (y) per la soppressione di fondo può essere rilevata dal diagramma [fig. H] come segue:	La distanza minima (y) para suprimir o fundo pode ser determinada com base no diagrama [cp. E] da seguinte:	La distanza minima (y) para suprimir o fundo pode ser determinada com base no diagramma [cp. E] da seguinte:	La distanza minima (y) para suprimir o fundo pode ser determinada com base no diagramma [cp. E] da seguinte:
Exemple: $x = 100 \text{ mm}$, $y = 7 > 7\% \text{ de } 100 \text{ mm} = 7 \text{ mm}$. C'est à dire que l'arrière-plan est masqué à partir d'une distance du capturé > 107.	Exemplo: $x = 100 \text{ mm}$, $y = 7 > 7\% \text{ de } 100 \text{ mm} = 7 \text{ mm}$. Isto significa, que o sensor suprime o plano de fundo a partir de uma distância > 107 mm do sensor.	Esempio: $x = 100 \text{ mm}$, $y = 7 > 7\% \text{ de } 100 \text{ mm} = 7 \text{ mm}$. Esto significa, que el sensor suprime el fondo a partir de una distancia > 107 mm del sensor.	Esempio: $x = 100 \text{ mm}$, $y = 7 > 7\% \text{ de } 100 \text{ mm} = 7 \text{ mm}$. Esto significa, que el sensor suprime el fondo a partir de una distancia > 107 mm del sensor.	Exemplo: $x = 100 \text{ mm}$, $y = 7 > 7\% \text{ de } 100 \text{ mm} = 7 \text{ mm}$. Esto significa, que el sensor suprime el fondo a partir de una distancia > 107 mm del sensor.	Exemplo: $x = 100 \text{ mm}$, $y = 7 > 7\% \text{ de } 100 \text{ mm} = 7 \text{ mm}$. Esto significa, que el sensor suprime el fondo a partir de una distancia > 107 mm del sensor.	Exemplo: $x = 100 \text{ mm}$, $y = 7 > 7\% \text{ de } 100 \text{ mm} = 7 \text{ mm}$. Esto significa, que el sensor suprime el fondo a partir de una distancia > 107 mm del sensor.
2 Monter le capteur sur une équerre de fixation adaptée (voir la gamme d'accessoires SICK).	2 Montar o sensor num suporte de fixação adequado (ver linha de acessórios da SICK).	2 Montare il sensore su un supporto di fissaggio adatto (vedi la gamma di accessori SICK).	2 Montar el sensor en una escuadra de fijación adecuada (véase el programa de accesorios SICK).	2 将传感器安装在合适的安装托架上（参见 SICK 附件说明书）。	2 将传感器安装在合适的安装托架上（参见 SICK 附件说明书）。	2 将传感器安装在合适的安装托架上（参见 SICK 附件说明书）。
Respecter le couple de serrage maximum autorisé du capteur de 0.8 Nm	Respetar o momento torque máximo permitido do sensor de 0.8 Nm.	Rispettare il momento torcente massimo consentito del sensore di 0.8 Nm.	Respetar la dirección preferencial del objeto en relación al sensor (cfr. A).	3 将传感器安装在扫描区域内时，注意物体的优先方向（参见 A）。	3 将传感器安装在扫描区域内时，注意物体的优先方向（参见 A）。	3 将传感器安装在扫描区域内时，注意物体的优先方向（参见 A）。
Tenir compte de la direction préférable de l'objet par rapport au capteur (voir [A]).	Respetar o sentido de direção preferencial do objecto relativamente ao sensor (ver [A]).	Respetare la direzione preferenziale dell'oggetto in relazione al sensore (cfr. A).	Respetar la dirección preferencial del objeto con respecto al sensor (U _b = 0 V).	3 必须在无电压状态 (U _b = 0 V) 连接传感器。依据不同连接类型，注意图 [参照 B] 中的信息：	3 必须在无电压状态 (U _b = 0 V) 连接传感器。依据不同连接类型，注意图 [参照 B] 中的信息：	3 必须在无电压状态 (U _b = 0 V) 连接传感器。依据不同连接类型，注意图 [参照 B] 中的信息：
3 Le raccordement des capteurs doit s'effectuer hors tension (U _b = 0 V). Selon le mode de raccordement, respecter les informations contenues dans les schémas [B]:	3 A conexão dos sensores deve ser realizada desligada (U _b = 0 V). Conforme o tipo de conexão, devem ser observadas as informações contidas nos gráficos [B]:	3 Il collegamento dei sensori deve avvenire in assenza di tensione (U _b = 0 V). In base al tipo di collegamento si devono rispettare le informazioni nei grafici [fig. B]:	3 Los sensores deben conectarse sin tensión (U _b = 0 V). Debe tenerse en cuenta la información de las figuras [fig. B] en función de cada tipo de conexión:	1 检查使用条件：使能通訊距離和背景抑制距離與圖表 [參照 H] 調整開關距離和物體距離。（ x = 物體距離， y = 已設置的開關距離和背景抑制距離）。	1 检查使用条件：使能通訊距離和背景抑制距離與圖表 [參照 H] 調整開關距離和物體距離。（ x = 物體距離， y = 已設置的開關距離和背景抑制距離）。	1 检查使用条件：使能通訊距離和背景抑制距離與圖表 [參照 H] 調整開關距離和物體距離。（ x = 物體距離， y = 已設置的開關距離和背景抑制距離）。
• Raccordement du connecteur : affectation des broches	• Cabo : correr das fios	• Collegamento a spina: assegnazione pin	• Conector: Pin-out	1 使用条件を認識してください: 検出範囲および対象物または背景への距離、ならびに対象物に対する背景抑制率を設定する図 [H] を参考して、検出範囲と検出範囲の % までの背景抑制率との間の移動距離 (対象物反射率/背景反射率)。反射率: 6% = 黒 (3), 18% = グレー (2), 90% = 白 (1) (DIN 5033 規定の標準)。	1 使用条件を認識してください: 検出範囲および対象物または背景への距離、ならびに対象物に対する背景抑制率を設定する図 [H] を参考して、検出範囲と検出範囲の % までの背景抑制率との間の移動距離 (対象物反射率/背景反射率)。反射率: 6% = 黒 (3), 18% = グレー (2), 90% = 白 (1) (DIN 5033 規定の標準)。	1 使用条件を認識してください: 検出範囲および対象物または背景への距離、ならびに対象物に対する背景抑制率を設定する図 [H] を参考して、検出範囲と検出範囲の % までの背景抑制率との間の移動距離 (対象物反射率/背景反射率)。反射率: 6% = 黒 (3), 18% = グレー (2), 90% = 白 (1) (DIN 5033 規定の標準)。
Instalar ou ligar a alimentação de tensão ($U_b > 0 \text{ V}$) somente após a conclusão de todas as conexões elétricas, reipristinando ou encerrando a alimentação de tensão ($U_b > 0 \text{ V}$). Sólido sensor se acende o indicador LED verde.	Instalar ou ligar a alimentação de tensão ($U_b > 0 \text{ V}$) somente após a conclusão de todas as conexões elétricas, reipristinando ou encerrando a alimentação de tensão ($U_b > 0 \text{ V}$). Sólido sensor se acende o indicador LED verde.	Instalar ou ligar a alimentação de tensão ($U_b > 0 \text{ V}$) somente após a conclusão de todas as conexões elétricas, reipristinando ou encerrando a alimentação de tensão ($U_b > 0 \text{ V}$). Sólido sensor se acende o indicador LED verde.	Instalar ou ligar a alimentação de tensão ($U_b > 0 \text{ V}$) somente após a conclusão de todas as conexões elétricas, reipristinando ou encerrando a alimentação de tensão ($U_b > 0 \text{ V}$). Sólido sensor se acende o indicador LED verde.	1 使用条件を認識してください: 検出範囲および対象物または背景への距離、ならびに対象物に対する背景抑制率を設定する図 [H] を参考して、検出範囲と検出範囲の % までの背景抑制率との間の移動距離 (対象物反射率/背景反射率)。反射率: 6% = 黒 (3), 18% = グレー (2), 90% = 白 (1) (DIN 5033 規定の標準)。	1 使用条件を認識してください: 検出範囲および対象物または背景への距離、ならびに対象物に対する背景抑制率を設定する図 [H] を参考して、検出範囲と検出範囲の % までの背景抑制率との間の移動距離 (対象物反射率/背景反射率)。反射率: 6% = 黒 (3), 18% = グレー (2), 90% = 白 (1) (DIN 5033 規定の標準)。	1 使用条件を認識してください: 検出範囲および対象物または背景への距離、ならびに対象物に対する背景抑制率を設定する図 [H] を参考して、検出範囲と検出範囲の % までの背景抑制率との間の移動距離 (対象物反射率/背景反射率)。反射率: 6% = 黒 (3), 18% = グレー (2), 90% = 白 (1) (DIN 5033 規定の標準)。
Sorties de commutation Q / O (selon le schéma B):	Apprentissage = apprentissage externe (ET) (voir le réglage)	Uscite di commutazione Q / O (secondo lo schema B):	Salidas de comutación Q / O (según el esquema B):	3 传感器的连接件应避免在带电情况下（ $U_b > 0 \text{ V}$ ）被触碰。	3 传感器的连接件应避免在带电情况下（ $U_b > 0 \text{ V}$ ）被触碰。	3 传感器的连接件应避免在带电情况下（ $U_b > 0 \text{ V}$ ）被触碰。
WTB4-3Exxx et WTB4-3Fxxx	Apprentissage = apprentissage externe (ET) (voir le réglage)	Uscite di commutazione Q / O (secondo lo schema B):	Salidas de comutación Q / O (según el esquema B):	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
D: commutation sombre, la sortie (Q) retombe lorsqu'un objet se trouve dans la zone de détection.	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
WTB4-3Exxx et WTB4-3Px1x	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
WTB4-3N1362 et WTB3Nx1x	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
L: commutation claire, la sortie (Q) commute lorsqu'un objet se trouve dans la zone de détection.	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
WTB4-3P1162 et WTB4-3N1162	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
WTB4-3Px262 et WTB4-3Nx262	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
ANT: sorties antivalentes Q / O / WTB4-3Nx26x	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
WTB4-3Px26x et WTB4-3Nx26x	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
WTB4-3Px1x et WTB4-3Px1xx	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。
WTB4-3N1362 et WTB3Nx1xx	Teach = Teach externo (ET) (ver Ajuste)	Salimento: color: colar do hilo	Salimento: color: colar do hilo	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接件：连接件可能带电。	3 请勿触碰连接