



# SRS50-HXA0-K21

SRS/SRM50

MOTOR FEEDBACK SYSTEMS

**SICK**  
Sensor Intelligence.

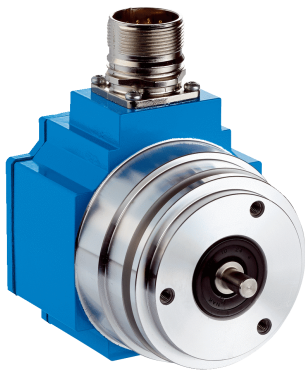


Illustration may differ



### Ordering information

Type	Part no.
SRS50-HXA0-K21	1037099

Other models and accessories → [www.sick.com/SRS\\_SRM50](http://www.sick.com/SRS_SRM50)

### Detailed technical data

#### Safety-related parameters

<b>MTTF<sub>D</sub> (mean time to dangerous failure)</b>	235 years (EN ISO 13849) <sup>1)</sup>
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<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Performance

<b>Sine/cosine periods per revolution</b>	1,024
<b>Number of the absolute ascertainable revolutions</b>	1
<b>Total number of steps</b>	32,768
<b>Measuring step</b>	0.3 " For interpolation of the sine/cosine signals with, e. g., 12 bits
<b>Integral non-linearity</b>	Typ. ± 45 ", Error limits for evaluating sine/cosine period
<b>Differential non-linearity</b>	± 7 "
<b>Operating speed</b>	≤ 6,000 min <sup>-1</sup> , up to which the absolute position can be reliably produced
<b>Available memory area</b>	128 Byte
<b>System accuracy</b>	± 52 "

#### Interfaces

<b>Type of code for the absolute value</b>	Binary
<b>Code sequence</b>	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing), For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)
<b>Communication interface</b>	HIPERFACE®

#### Electrical data

<b>Connection type</b>	Male connector, M23, 12-pin, radial
<b>Supply voltage</b>	7 V DC ... 12 V DC
<b>Recommended supply voltage</b>	8 V DC

<sup>1)</sup> Without load.

<b>Current consumption</b>	80 mA <sup>1)</sup>
<b>Output frequency for sine/cosine signals</b>	≤ 200 kHz

<sup>1)</sup> Without load.

### Mechanical data

<b>Shaft version</b>	Solid shaft
<b>Shaft diameter</b>	6 mm
<b>Flange type / stator coupling</b>	Servo flange, stator coupling
<b>Dimensions</b>	See dimensional drawing
<b>Weight</b>	≤ 0.2 kg
<b>Moment of inertia of the rotor</b>	25 gcm <sup>2</sup>
<b>Operating speed</b>	≤ 12,000 min <sup>-1</sup>
<b>Angular acceleration</b>	≤ 200,000 rad/s <sup>2</sup>
<b>Operating torque</b>	1 Ncm
<b>Start up torque</b>	+ 1.5 Ncm
<b>Permissible shaft loading</b>	40 N (radial) 20 N (axial)
<b>Life of ball bearings</b>	3.6 x 10 <sup>9</sup> revolutions

### Ambient data

<b>Operating temperature range</b>	-30 °C ... +85 °C
<b>Storage temperature range</b>	-30 °C ... +90 °C, without package
<b>Relative humidity/condensation</b>	90 %, Condensation not permitted
<b>Resistance to shocks</b>	100 g, 10 ms, 10 ms (according to EN 60068-2-27)
<b>Frequency range of resistance to vibrations</b>	20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)
<b>EMC</b>	According to EN 61000-6-2 and EN 61000-6-3 <sup>1)</sup>
<b>Enclosure rating</b>	IP65, with mating connector inserted (IEC 60529)

<sup>1)</sup> The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

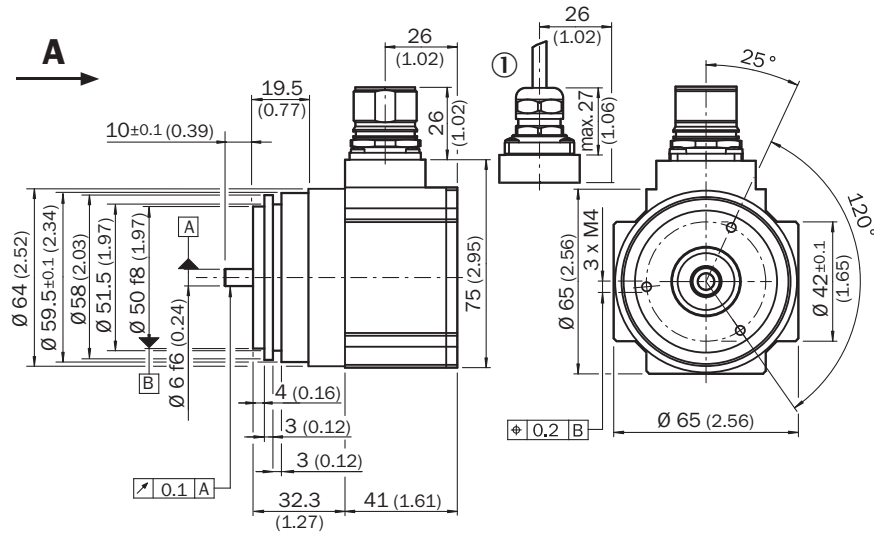
### Classifications

<b>ECLASS 5.0</b>	27270590
<b>ECLASS 5.1.4</b>	27270590
<b>ECLASS 6.0</b>	27270590
<b>ECLASS 6.2</b>	27270590
<b>ECLASS 7.0</b>	27270590
<b>ECLASS 8.0</b>	27270590
<b>ECLASS 8.1</b>	27270590
<b>ECLASS 9.0</b>	27270590
<b>ECLASS 10.0</b>	27273805
<b>ECLASS 11.0</b>	27273901
<b>ECLASS 12.0</b>	27273901
<b>ETIM 5.0</b>	EC001486

<b>ETIM 6.0</b>	EC001486
<b>ETIM 7.0</b>	EC001486
<b>ETIM 8.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

### Dimensional drawing (Dimensions in mm (inch))

Solid shaft, face mount flange, stand-alone

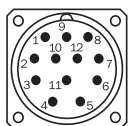
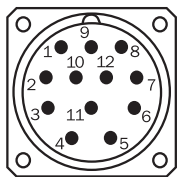


General tolerances according to DIN ISO 2768-mk

① R = min. bending radius 40 mm

### PIN assignment

View of the M23 male connector plug-in face



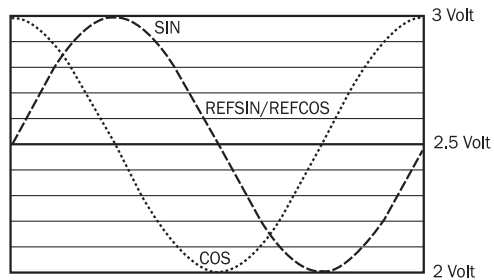
Ansicht Steckseite

Schirmanschluss am Steckergehäuse

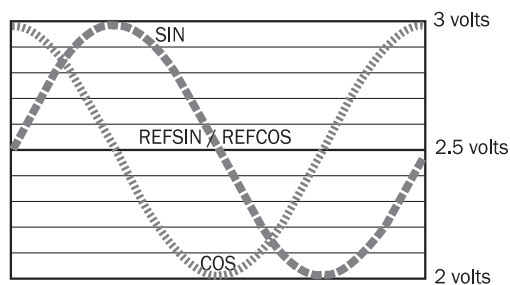
N. C. = Not connected

## Diagrams

Signal specification of the process channel








Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing) 1 period = 360° : 1024



## Recommended accessories

Other models and accessories → [www.sick.com/SRS\\_SRM50](http://www.sick.com/SRS_SRM50)

	Brief description	Type	Part no.
Programming and configuration tools			
	SVip® LAN programming tool for all motor feedback systems	PGT-11-S LAN	1057324
Spare parts			
	BEF-MK-S02	BEF-MK-S02	2074582
Others			
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M23, 12-pin, straight</li> <li>• <b>Connection type head B:</b> Flying leads</li> <li>• <b>Signal type:</b> HIPERFACE®</li> <li>• <b>Cable:</b> 3 m, 8-wire, PUR, halogen-free</li> <li>• <b>Description:</b> HIPERFACE®, shielded</li> </ul>	DOL-2308-G03MJB2	2031070
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M23, 12-pin, straight</li> <li>• <b>Connection type head B:</b> Flying leads</li> <li>• <b>Signal type:</b> HIPERFACE®</li> <li>• <b>Cable:</b> 5 m, 8-wire, PUR, halogen-free</li> <li>• <b>Description:</b> HIPERFACE®, shielded</li> </ul>	DOL-2308-G05MJB2	2031071
	DOL-2308-G1M5JB2	DOL-2308-G1M5JB2	2031069

	Brief description	Type	Part no.
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M23, 12-pin, straight</li> <li>• <b>Connection type head B:</b> Flying leads</li> <li>• <b>Signal type:</b> HIPERFACE®</li> <li>• <b>Cable:</b> 10 m, 8-wire, PUR, halogen-free</li> <li>• <b>Description:</b> HIPERFACE®, shielded</li> </ul>	DOL-2308-G10MJB2	2031072
	<ul style="list-style-type: none"> <li>• <b>Connection type head A:</b> Female connector, M23, 12-pin, straight</li> <li>• <b>Connection type head B:</b> Flying leads</li> <li>• <b>Signal type:</b> HIPERFACE®</li> <li>• <b>Cable:</b> 15 m, 8-wire, PUR, halogen-free</li> <li>• <b>Description:</b> HIPERFACE®, shielded</li> </ul>	DOL-2308-G15MJB2	2031073

## SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

## WORLDWIDE PRESENCE:

Contacts and other locations –[www.sick.com](http://www.sick.com)