

# DBS60E-TGEZAS164

DBS60

**INCREMENTAL ENCODERS**

**SICK**  
Sensor Intelligence.

Illustration may differ

### Ordering information

Type	Part no.
DBS60E-TGEZAS164	1126431

Other models and accessories → [www.sick.com/DBS60](http://www.sick.com/DBS60)



### Detailed technical data

#### Features

<b>Special device</b>	✓
<b>Specialty</b>	M12 male connector, 4-pin, radial HTL preprogrammed
<b>Standard reference device</b>	DBS60E-TGFCA2048, 1076604

#### Safety-related parameters

<b>MTTF<sub>D</sub> (mean time to dangerous failure)</b>	500 years (EN ISO 13849-1) <sup>1)</sup>
--	--

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Performance

<b>Pulses per revolution</b>	8
<b>Measuring step</b>	≤ 90 °, electric/pulses per revolution
<b>Measuring step deviation</b>	± 18 ° / pulses per revolution
<b>Error limits</b>	Measuring step deviation x 3
<b>Duty cycle</b>	≤ 0.5 ± 5 %

#### Interfaces

<b>Communication interface</b>	Incremental
<b>Communication Interface detail</b>	HTL <sup>1)</sup>
<b>Number of signal channels</b>	6-channel
<b>Initialization time</b>	< 5 ms <sup>2)</sup>
<b>Output frequency</b>	+ 300 kHz <sup>3)</sup>
<b>Load current</b>	≤ 30 mA, per channel
<b>Power consumption</b>	≤ 0.5 W (without load)

<sup>1)</sup> Output level depends on the supply voltage.

<sup>2)</sup> Valid signals can be read once this time has elapsed.

<sup>3)</sup> Up to 450 kHz on request.

#### Electronics

<b>Connection type</b>	Special version
------------------------	-----------------

<sup>1)</sup> Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

<b>Connection type Detail</b>	M12 male connector, 4-pin, radial
<b>Supply voltage</b>	4.5 ... 30 V
<b>Reference signal, number</b>	1
<b>Reference signal, position</b>	90°, electric, logically gated with A and B
<b>Reverse polarity protection</b>	✓
<b>Short-circuit protection of the outputs</b>	✓ <sup>1)</sup>

<sup>1)</sup> Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

## Mechanics

<b>Mechanical design</b>	Through hollow shaft
<b>Shaft diameter</b>	14 mm
<b>Flange type / stator coupling</b>	Without stator coupling, flange with 4 x M2,5
<b>Weight</b>	+ 0.25 kg <sup>1)</sup>
<b>Shaft material</b>	Stainless steel
<b>Flange material</b>	Aluminum
<b>Housing material</b>	Aluminum
<b>Start up torque</b>	+ 0.5 Ncm (+20 °C)
<b>Operating torque</b>	0.4 Ncm (+20 °C)
<b>Permissible movement static</b>	± 0.3 mm (radial) ± 0.5 mm (axial) <sup>2)</sup>
<b>Permissible movement dynamic</b>	± 0.1 mm (radial) ± 0.2 mm (axial) <sup>2)</sup>
<b>Operating speed</b>	6,000 min <sup>-1</sup> <sup>3)</sup>
<b>Maximum operating speed</b>	9,000 min <sup>-1</sup> <sup>4)</sup>
<b>Moment of inertia of the rotor</b>	50 gcm <sup>2</sup>
<b>Bearing lifetime</b>	3.6 x 10 <sup>9</sup> revolutions
<b>Angular acceleration</b>	≤ 500,000 rad/s <sup>2</sup>

<sup>1)</sup> Based on encoder with male connector or cable with male connector.

<sup>2)</sup> Not applicable for stator coupling type C and K.

<sup>3)</sup> Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

<sup>4)</sup> Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

## Ambient data

<b>EMC</b>	According to EN 61000-6-2 and EN 61000-6-3
<b>Enclosure rating</b>	IP65, housing side (IEC 60529) <sup>1)</sup> IP65, shaft side (IEC 60529)
<b>Permissible relative humidity</b>	90 % (Condensation not permitted)
<b>Operating temperature range</b>	-30 °C ... +100 °C, at maximum 3,000 pulses per revolution <sup>2)</sup>
<b>Storage temperature range</b>	-40 °C ... +100 °C, without package
<b>Resistance to shocks</b>	250 g, 3 ms (EN 60068-2-27)
<b>Resistance to vibration</b>	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

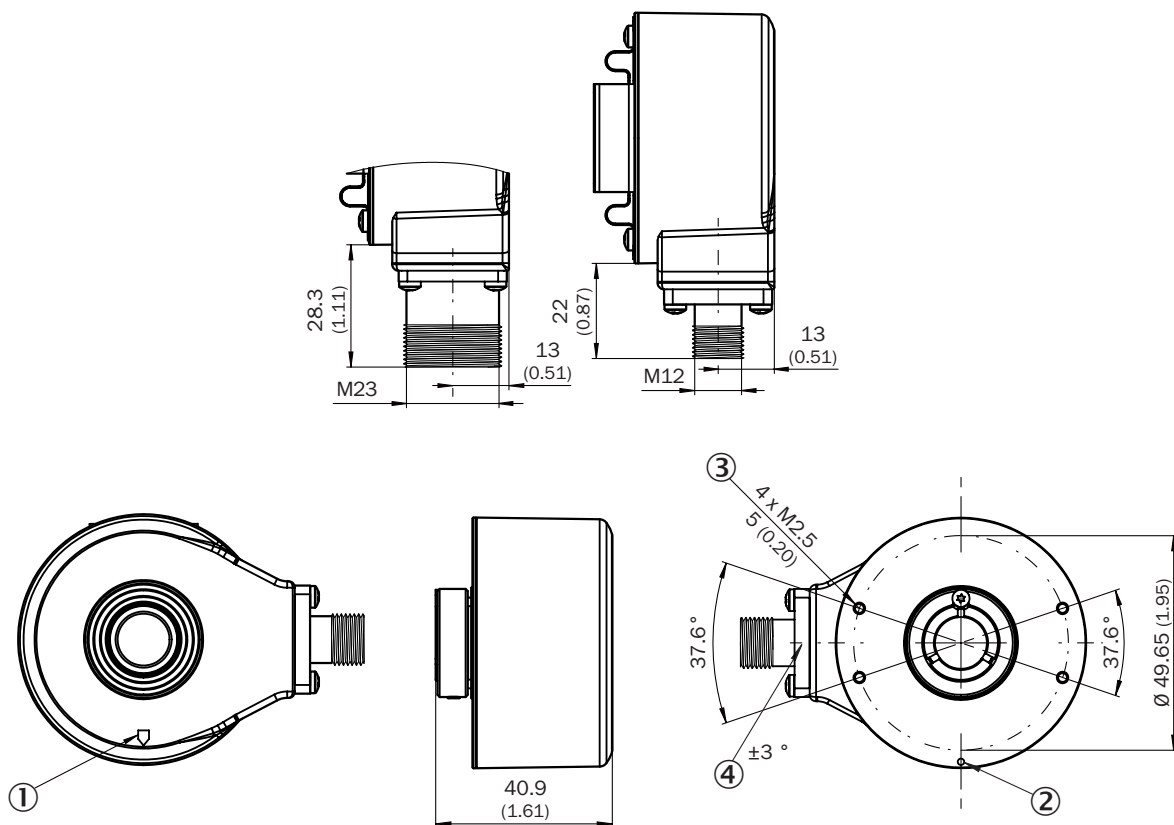
<sup>1)</sup> With mating connector fitted.

<sup>2)</sup> These values relate to all mechanical versions including recommended accessories unless otherwise noted.

### Classifications

<b>ECLASS 5.0</b>	27270501
<b>ECLASS 5.1.4</b>	27270501
<b>ECLASS 6.0</b>	27270590
<b>ECLASS 6.2</b>	27270590
<b>ECLASS 7.0</b>	27270501
<b>ECLASS 8.0</b>	27270501
<b>ECLASS 8.1</b>	27270501
<b>ECLASS 9.0</b>	27270501
<b>ECLASS 10.0</b>	27270501
<b>ECLASS 11.0</b>	27270501
<b>ECLASS 12.0</b>	27270501
<b>ETIM 5.0</b>	EC001486
<b>ETIM 6.0</b>	EC001486
<b>ETIM 7.0</b>	EC001486
<b>ETIM 8.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

### Dimensional drawing (Dimensions in mm (inch))



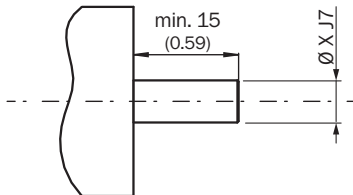
XF7 values see shaft diameter table for through hollow shaft, clamping at the front

- ① Zero pulse mark on housing
- ② Zero pulse mark on flange
- ③ Depth
- ④ Male connector tolerance in relation to hole pattern

Type Through hollow shaft with front clamping	Shaft diameter XF7
DBS60x-TAxxxxxxx DBS60x-T1xxxxxxx	6 mm
DBS60x-TBxxxxxxx DBS60x-T2xxxxxxx	8 mm
DBS60x-TCxxxxxxx DBS60x-T3xxxxxxx	3/8"
DBS60x-TDxxxxxxx DBS60x-T4xxxxxxx	10 mm
DBS60x-TExxxxxxx DBS60x-T5xxxxxxx	12 mm
DBS60x-TFxxxxxxx DBS60x-T6xxxxxxx	1/2"
DBS60x-TGxxxxxxx DBS60x-T7xxxxxxx	14 mm
DBS60x-THxxxxxxx DBS60x-T8xxxxxxx	15 mm
DBS60x-TJxxxxxxx	5/8"

### Attachment specifications

Through hollow shaft with front clamping

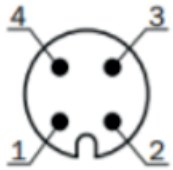


Customer side

Type Through hollow shaft with front clamping	Shaft diameter xj7
DBS60x-TAxxxxxxx DBS60x-T1xxxxxxx	6 mm
DBS60x-TBxxxxxxx DBS60x-T2xxxxxxx	8 mm
DBS60x-TCxxxxxxx DBS60x-T3xxxxxxx	3/8"
DBS60x-TDxxxxxxx DBS60x-T4xxxxxxx	10 mm
DBS60x-TExxxxxxx DBS60x-T5xxxxxxx	12 mm
DBS60x-TFxxxxxxx DBS60x-T6xxxxxxx	1/2"
DBS60x-TGxxxxxxx	14 mm

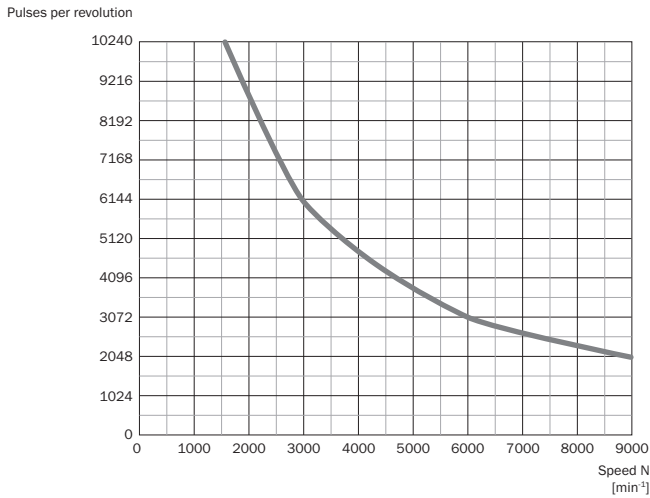
Type Through hollow shaft with front clamping	Shaft diameter xj7
DBS60x-T7xxxxxxx	15 mm
DBS60x-THxxxxxxx DBS60x-T8xxxxxxx	
DBS60x-TJxxxxxxx	
	5/8"

### PIN assignment



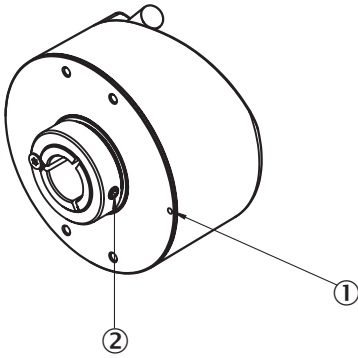
Pin No.	Signal	Explanation
1	Us	Supply voltage
2	B	Signal line
3	Gnd	Ground connection
4	A	Signal line

### Diagrams



## Operation note

Hollow shaft



Attention! If stator coupling is mounted, the zero pulse mark can be hidden by the stator coupling

- ① Zero pulse mark on flange
- ② Zero pulse is active when screw of clamping is inline with zero pulse mark on flange or housing mark

## SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

## WORLDWIDE PRESENCE:

Contacts and other locations –[www.sick.com](http://www.sick.com)