

DFV60A-22PC00S04

DFV60

MEASURING WHEEL ENCODERS





Ordering information

Туре	Part no.
DFV60A-22PC00S04	1082234

DFV60 spring arm (part number: 2056155) not included with delivery

Other models and accessories → www.sick.com/DFV60

Illustration may differ



Detailed technical data

Features

Special device	✓
Specialty	Pulses per revolution programmable up to 65536, preprogrammed to 1000 by factory Preprogrammed to 1000 by factory
Standard reference device	DFV60A-22PC65536, 1051309
Items supplied	DFV60 spring arm (part number: 2056155) not included with delivery

Performance

Pulses per revolution	1,000
Resolution in pulses/mm	3.33 Pulses/mm ¹⁾
Measuring increment (resolution in mm/ pulse)	0.3 mm/pulse ²⁾
Measuring step deviation	± 0.008° ³⁾
Error limits	\pm 4 mm/m, subject to measuring wheel (measuring wheel surface + measuring surface + ambient conditions)
Initialization time	30 ms

¹⁾ Calculation example: Pulses per revolution / measuring wheel circumference = 16,384 pulses per revolution / 200 mm = 81.92 pulses/mm.

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / HTL
Programmable/configurable	✓

Electrical data

Connection type	Male connector, M12, 8-pin, radial
Power consumption max. without load	≤ 30 mA

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

 $^{^{2)} \ \}text{Calculation example: Circumference of wheel / pulses per revolution = 200 mm / 16384 \ pulses per revolution = 0,012 mm/pulse.}$

 $^{^{}m 3)}$ Value refers to the mounted encoder.

Supply voltage	4.5 V 32 V
Load current max.	30 mA
Maximum output frequency	820 kHz
Reference signal, number	1
Reference signal, position	$90^{\circ},$ electric, logically gated with A and B
Reverse polarity protection	√
Short-circuit protection of the outputs	√
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) ¹⁾

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Mechanical data

Measuring wheel circumference	300 mm
Measuring wheel surface	O-ring NBR70 ¹⁾
Mass	+ 500 g
Encoder material	
Shaft	Stainless steel
Flange	Aluminum
Housing	Aluminum
Cable	PUR
Spring arm mechanism material	
Spring element	Not contained in the scope of delivery of the system
Measuring wheel, spring arm	Aluminum
Start up torque	0.8 Ncm (at 20 °C)
Operating torque	0.6 Ncm (at 20 °C)
Operating speed	1,500 min ⁻¹
Maximum operating speed	3,000 min ^{-1 2)}
Bearing lifetime	3 x 10^9 revolutions
Maximum travel/deflection of spring arm	40 mm
Max. permissible working area for the spring (continuous operation)	± 10 mm
Recommended spring deflection	20 mm 40 mm
Mounting position relative to the measuring object	Preferably from above, from below possible

¹⁾ The surface of a measuring wheel is subject to wear. This depends on contact pressure, acceleration behavior in the application, traversing speed, measurement surface, mechanical alignment of the measuring wheel, temperature, and ambient conditions. We recommend you regularly check the condition of the measuring wheel and replace as required.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-4
Enclosure rating	IP65
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-20 °C +100 °C

 $^{^{2)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

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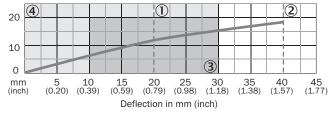
MEASURING WHEEL ENCODERS

Storage temperature range	-40 °C +100 °C, without package
Classifications	
ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270790
ECLASS 11.0	27270707
ECLASS 12.0	27270504
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

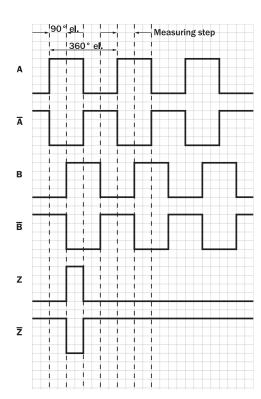
Diagrams

Dual wheel, spring tension, yoke mount

Force in N



- ① Recommended pre-tension (20 mm)
- ② Maximum deflection (40 mm)
- $\ensuremath{ \begin{tabular}{ll} \ensuremath{ \begin{tabular}{l$
- ④ Permissible working area (0 30 mm)



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