



# DFS60B-S1PK00S03

DFS60

INCREMENTAL ENCODERS

**SICK**  
Sensor Intelligence.



Illustration may differ



### Ordering information

Type	Part no.
DFS60B-S1PK00S03	1111736

Other models and accessories → [www.sick.com/DFS60](http://www.sick.com/DFS60)

### Detailed technical data

#### Features

<b>Special device</b>	✓
<b>Specialty</b>	Pulses per revolution: preprogrammed to 3600
<b>Standard reference device</b>	1036757, DFS60B-S1PK10000

#### Safety-related parameters

<b>MTTF<sub>D</sub> (mean time to dangerous failure)</b>	300 years (EN ISO 13849-1) <sup>1)</sup>
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<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Performance

<b>Pulses per revolution</b>	3,600 <sup>1)</sup>
<b>Measuring step</b>	90°, electric/pulses per revolution
<b>Measuring step deviation at non binary number of lines</b>	± 0.01°
<b>Error limits</b>	± 0.05°

<sup>1)</sup> See maximum revolution range.

#### Interfaces

<b>Communication interface</b>	Incremental
<b>Communication Interface detail</b>	TTL / HTL
<b>Factory setting</b>	Factory setting: output level TTL
<b>Number of signal channels</b>	6-channel
<b>Programmable/configurable</b>	✓
<b>Initialization time</b>	32 ms, 30 ms <sup>1)</sup>
<b>Output frequency</b>	≤ 600 kHz
<b>Load current</b>	≤ 30 mA
<b>Power consumption</b>	≤ 0.7 W (without load)

<sup>1)</sup> With mechanical zero pulse width.

## Electronics

<b>Connection type</b>	Cable, 8-wire, universal, 1.5 m <sup>1)</sup>
<b>Supply voltage</b>	4.5 ... 32 V
<b>Reference signal, number</b>	1
<b>Reference signal, position</b>	90°, electric, logically gated with A and B
<b>Reverse polarity protection</b>	✓
<b>Short-circuit protection of the outputs</b>	✓ <sup>2) 3)</sup>

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

<sup>2)</sup> Programming TTL with  $\geq 5.5$  V: short-circuit opposite to another channel or GND permissible for maximum 30 s.

<sup>3)</sup> Programming HTL or TTL with  $< 5.5$  V: short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

## Mechanics

<b>Mechanical design</b>	Solid shaft, Servo flange
<b>Shaft diameter</b>	6 mm With face
<b>Shaft length</b>	10 mm
<b>Weight</b>	+ 0.3 kg
<b>Shaft material</b>	Stainless steel
<b>Flange material</b>	Aluminum
<b>Housing material</b>	Aluminum die cast
<b>Start up torque</b>	0.5 Ncm (+20 °C)
<b>Operating torque</b>	0.3 Ncm (+20 °C)
<b>Permissible shaft loading</b>	80 N (radial) 40 N (axial)
<b>Operating speed</b>	$\leq 9,000 \text{ min}^{-1}$ <sup>1)</sup>
<b>Moment of inertia of the rotor</b>	6.2 gcm <sup>2</sup>
<b>Bearing lifetime</b>	3.6 x 10 <sup>10</sup> revolutions
<b>Angular acceleration</b>	$\leq 500,000 \text{ rad/s}^2$

<sup>1)</sup> Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

## Ambient data

<b>EMC</b>	According to EN 61000-6-2 and EN 61000-6-3
<b>Enclosure rating</b>	IP67, housing side, cable connection (IEC 60529) IP65, shaft side (IEC 60529)
<b>Permissible relative humidity</b>	90 % (Condensation not permitted)
<b>Operating temperature range</b>	-40 °C ... +100 °C <sup>1)</sup> -30 °C ... +100 °C <sup>2)</sup>
<b>Storage temperature range</b>	-40 °C ... +100 °C, without package
<b>Resistance to shocks</b>	70 g, 6 ms (EN 60068-2-27)
<b>Resistance to vibration</b>	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

<sup>1)</sup> Stationary position of the cable.

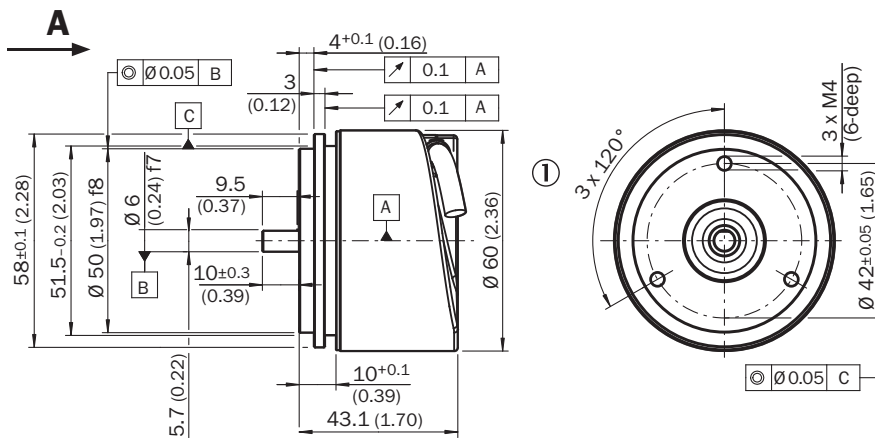
<sup>2)</sup> Flexible position of the cable.

## Classifications

<b>ECLASS 5.0</b>	27270501
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<b>ECLASS 5.1.4</b>	27270501
<b>ECLASS 6.0</b>	27270590
<b>ECLASS 6.2</b>	27270590
<b>ECLASS 7.0</b>	27270501
<b>ECLASS 8.0</b>	27270501
<b>ECLASS 8.1</b>	27270501
<b>ECLASS 9.0</b>	27270501
<b>ECLASS 10.0</b>	27270501
<b>ECLASS 11.0</b>	27270501
<b>ECLASS 12.0</b>	27270501
<b>ETIM 5.0</b>	EC001486
<b>ETIM 6.0</b>	EC001486
<b>ETIM 7.0</b>	EC001486
<b>ETIM 8.0</b>	EC001486
<b>UNSPSC 16.0901</b>	41112113

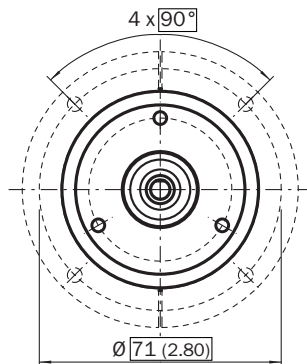
### Dimensional drawing (Dimensions in mm (inch))



① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

### Attachment specifications

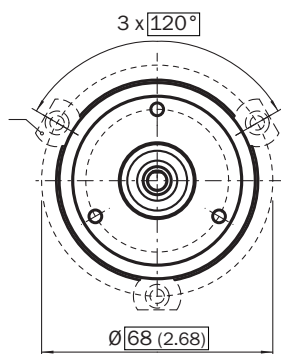
Mounting requirements for half-shell servo clamp



All dimensions in mm (inch)

Part no. 2029165

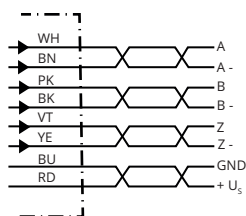
Mounting requirements for small servo clamp



All dimensions in mm (inch)

Part no. 2029166

### PIN assignment



PIN Male connector M12, 8-pin	PIN Male connector M23, 12-pin	Wire colors (cable connection)	TTL/HTL signal	Sin/Cos 1.0 V <sub>PP</sub>	Explanation
1	6	Brown	$\bar{A}$	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	$\bar{B}$	SIN-	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	$\bar{Z}$	$\bar{Z}$	Signal wire
6	3	Purple	Z	Z	Signal wire

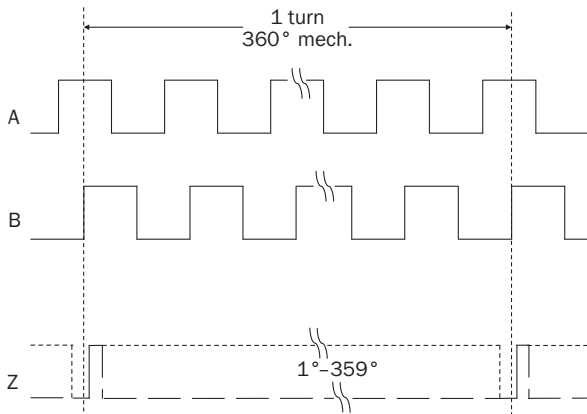
PIN Male connector M12, 8-pin	PIN Male connector M23, 12-pin	Wire colors (cable connection)	TTL/HTL signal	Sin/Cos 1.0 V <sub>pp</sub>	Explanation
7	10	Blue	GND	GND	Ground connection
8	12	Red	+U <sub>S</sub>	+U <sub>S</sub>	Supply voltage
-	9	-	N.c.	N.c.	Not assigned
-	2	-	N.c.	N.c.	Not assigned
-	11	-	N.c.	N.c.	Not assigned
-	7 <sup>1)</sup>	Orange	0-SET <sup>1)</sup>	N.c.	Set zero pulse <sup>1)</sup>
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

1)

For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

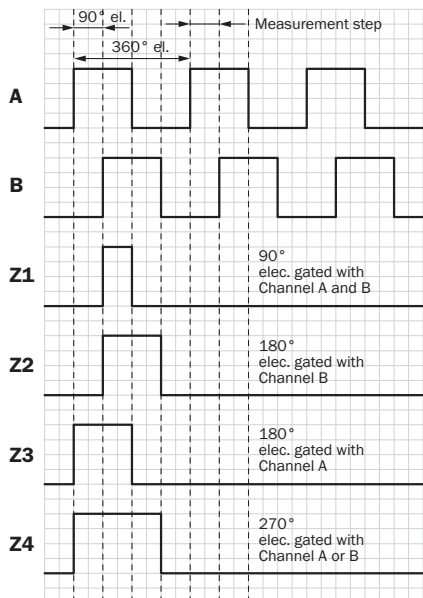
### Diagrams

Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



Supply voltage	Output
4,5 V ... 32 V	TTL/HTL programmable

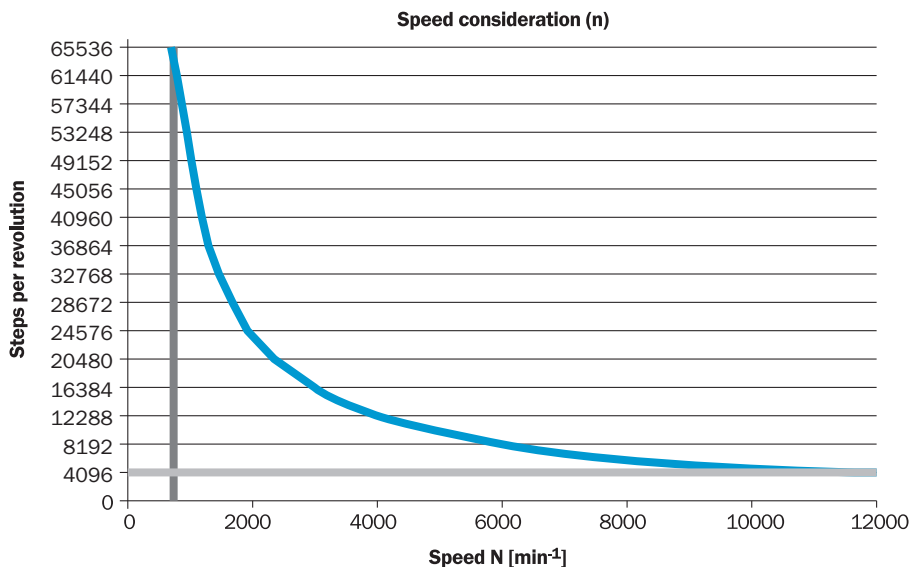
Electrical zero pulse width can be configured to 90°, 180°, or 270°. Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V ... 32 V	TTL/HTL programmable

Maximum revolution range



## SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

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